# Mathematical Derivations of Semianalytical Solutions for Pumping-Induced Drawdown and Stream Depletion in a Leaky Aquifer System

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KANSAS GEOLOGICAL SURVEY OPEN-FILE REPORT #2005-10

April 26, 2005

#### I. Introduction

In this report, derivations of the transform-space solutions to the mathematical model describing the drawdown and stream depletion produced by a pumping well in a leaky aquifer system are presented. The back transforms of these expressions are used by *Butler et al.* [in review] to develop new insights into stream-aquifer interactions in a leaky aquifer system.

In Section II of this report, governing equations and auxiliary conditions for a leaky aquifer system hydraulically connected to a stream are presented. The corresponding equations in Laplace-Fourier space are derived in Sections III and IV using standard integral transform methods. The general transform-space solution is presented in Section V. In Sections VI and VII, simplified solutions for an unbounded domain and an unbounded homogeneous domain, respectively, are presented. The derivation of a solution for the stream-depletion rate is presented in Section VIII. The methods used to numerically invert the transform-space solutions are described briefly in Section IX.

#### **II.** Governing Equations

The problem of interest here is that of the drawdown and stream depletion produced by pumping from a fully penetrating well in the leaky aquifer system of Figure 1. Following the approach of *Butler et al.* [2001], vertical flow within the upper aquifer is neglected (Dupuit assumptions). The stream and upper aquifer are separated by a zone of relatively low hydraulic conductivity, which is represented mathematically as an incompressible layer (*Hantush* [1965]). Portions of the upper aquifer underneath the stream are confined, but can be confined or unconfined elsewhere. Flow in the aquitard is incorporated using the model of *Hantush* [1960], which includes aquitard storage but neglects lateral flow. Similar to *Hantush and Jacob* [1955], the underlying (lower) aquifer is assumed to be a unit of relatively high permeability so that heads within that aquifer are unaffected by pumping in the upper aquifer. Hydraulic properties are assumed to be a function of x, but can be linearized into a series of zones of uniform properties that are arranged parallel to the stream. Any number of zones can be considered in this derivation but three are used in *Butler et al.* [in review].

Following the approach of *Butler et al.* [2001], governing equations and auxiliary conditions can be defined for the leaky aquifer system of Fig. 1.

Aquifer Flow

$$\frac{\partial^2 s(x, y, t)}{\partial x^2} + \frac{\partial^2 s(x, y, t)}{\partial y^2} - \frac{k_{sb}}{b_{sb}T(x)} s(x, y, t) \left(\mathcal{H}(x - x_{sl}) - \mathcal{H}(x - x_{sr})\right)$$

$$- \frac{k_c(x)}{T(x)} \frac{\partial s_c(x, y, z, t)}{\partial z} \bigg|_{z=0} + \frac{Q}{T(x)} \delta(x - x_p) \delta(y)$$

$$= \frac{S(x)}{T(x)} \frac{\partial s(x, y, t)}{\partial t} \qquad x_{lb} < x < x_{rb}, \qquad -\infty < y < \infty, \qquad t > 0$$
(1)

Note that Eq. (1) is a condensed but generalized form of Eq. (1)-(3) in *Butler et al.* [in review].

Initial condition,

$$s(x, y, t = 0) = 0$$
 (2)

Left boundary condition in x can be either constant head (Dirichlet condition),

$$s(x,y,t)\Big|_{x=x_{lb}} = 0 \tag{3}$$

or no flow (Neumann condition),

$$\left. \frac{\partial s(x,y,t)}{\partial x} \right|_{x=x_{lb}} = 0 \tag{4}$$

Similarly, right boundary condition in x can be,

$$s(x,y,t)\Big|_{x=x_{rb}} = 0 \tag{5}$$

or

$$\left. \frac{\partial s(x,y,t)}{\partial x} \right|_{x=x_{rb}} = 0 \tag{6}$$

Drawdown at infinity in y is bounded,

$$s(x, y = -\infty, t) < \infty \tag{7}$$

$$s(x, y = \infty, t) < \infty \tag{8}$$

A Cauchy boundary condition could also be readily incorporated into this development. However, for large  $x_{lb}$  and  $x_{rb}$ , the solution is not sensitive to the form of the lateral boundary conditions.

Aquitard

$$\frac{\partial^2 s_c(x, y, z, t)}{\partial z^2} = \frac{S_{Sc}(x)}{k_c(x)} \frac{\partial s_c(x, y, z, t)}{\partial t}$$

$$x_{lb} < x < x_{rb}, \quad -\infty < y < \infty, \qquad -b_c < z < 0, \qquad t > 0$$
(9)

Eq. (9) is equivalent to Eq. (4) in *Butler et al.* [in review].

Initial condition,

$$s_c(x, y, z, t = 0) = 0 \tag{10}$$

Continuity condition at interface of aquitard and upper aquifer,

$$s_c(x, y, z = 0, t) = s(x, y, t)$$
 (11)

Constant head at base of aquitard,

$$s_c(x, y, z = -b_c, t) = 0$$
 (12)

where

x, y =Cartesian coordinates in lateral plane. The origin of the x-axis can be any arbitrary location (e.g., origin defined at right bank of stream in *Butler et al.* [in review]) and the values increase from left to right. The origin of the y axis is at the pumping well and the values increase upward, [L];

z = vertical distance from bottom of upper aquifer, [L]; t = time, [T]; 
$$\begin{split} s(x,y,t) &= \text{drawdown in the upper aquifer, } [L];\\ T(x) &= \text{transmissivity of the upper aquifer, } [L];\\ S(x) &= \text{specific yield or storativity of the upper aquifer, } [1];\\ k_{sb} &= \text{hydraulic conductivity of streambed, } [L/T];\\ b_{sb} &= \text{streambed thickness, } [L];\\ \mathcal{H}(x-x_{sl}) &= \text{Heaviside function } (=0 \text{ for } x-x_{sl} < 0, =1 \text{ for } x-x_{sl} > 0), \text{ respectively;}\\ x_{sl}, x_{sr} &= \text{left and right boundary of the stream, respectively } [L];\\ s_c(x,y,z,t) &= \text{drawdown in the aquitard, } [L];\\ S_{Sc}(x) &= \text{specific storage of the aquitard, } [L^{-1}];\\ k_c(x) &= \text{hydraulic conductivity of aquitard, } [L/T];\\ b_c(x) &= \text{thickness of aquitard, } [L];\\ x_{lb}, x_{rb} &= \text{left and right boundary of the aquifer, respectively, } [L];\\ x_p &= x \text{ coordinate of pumping well, } [L];\\ Q &= \text{pumping rate from well located at } (x_p, 0), [L^3/T]. \end{split}$$

A constant rate of pumping is assumed for this development. A variable rate of pumping or a cyclic pumping strategy could be readily incorporated using standard convolution approaches (*Wallace et al.* [1990])

Notation used in this report is the same as that used in the Mathematica package developed for this project and may differ from that used in *Butler et al.* [in review] because of the notation rules for Mathematica and the more generalized form of this development.



Figure 1: Schematic (a) cross-sectional and (b) areal views of the stream-aquifer system considered in this paper (notation explained in text; stream depletion in this configuration consists of vertical leakage across the low-permeability streambed).

### **III.** Laplace Space Equations

Applying a Laplace transform in t to the equations of the previous section yields

$$\frac{\partial^2 \overline{s}(x,y)}{\partial x^2} + \frac{\partial^2 \overline{s}(x,y)}{\partial y^2} - \frac{k_{sb}}{b_{sb}T(x)} \overline{s}(x,y) \left(\mathcal{H}(x-x_{sl}) - \mathcal{H}(x-x_{sr})\right) - \frac{k_c(x)}{T(x)} \frac{\partial \overline{s}_c(x,y,z)}{\partial z} \bigg|_{z=0} + \frac{Q}{pT(x)} \delta(x-x_p) \delta(y) = p \frac{S(x)}{T(x)} \overline{s}(x,y) \qquad x_{lb} < x < x_{rb}, \qquad -\infty < y < \infty$$
(13)

$$\overline{s}(x,y)\Big|_{x=x_{lb}} = 0 \qquad or \qquad \frac{\partial \overline{s}(x,y)}{\partial x}\Big|_{x=x_{lb}} = 0 \tag{14}$$

$$\overline{s}(x,y)\Big|_{x=x_{rb}} = 0 \qquad or \qquad \frac{\partial \overline{s}(x,y)}{\partial x}\Big|_{x=x_{rb}} = 0 \tag{15}$$

$$\overline{s}(x, y = -\infty) < \infty$$
 and  $\overline{s}(x, y = \infty) < \infty$  (16)

$$\frac{\partial^2 \overline{s}_c(x, y, z)}{\partial z^2} = p \frac{S_{Sc}(x)}{k_c(x)} \overline{s}_c(x, y, z)$$
$$x_{lb} < x < x_{rb}, \quad -\infty < y < \infty, \qquad -b_c < z < 0$$
(17)

$$\overline{s}_c(x, y, z = 0) = \overline{s}(x, y) \tag{18}$$

$$\overline{s}_c(x, y, z = -b_c) = 0 \tag{19}$$

where  $\overline{s}$  and  $\overline{s_c}$  are the Laplace transform of s and  $s_c$ , respectively, and p is the Laplace transform parameter. Note the overbar is used to indicate the dependence of s and  $s_c$  on p.

After applying the boundary conditions, the general solution for  $s_c$  at any z and its first derivative at z = 0 are, respectively,

$$\overline{s}_{c}(x, y, z) = \cosh\left[\sqrt{\frac{S_{Sc}(x)p}{k_{c}(x)}}z\right]\overline{s}(x, y) + \coth\left[\sqrt{\frac{S_{Sc}(x)p}{k_{c}(x)}}\right]\sinh\left[\sqrt{\frac{S_{Sc}(x)p}{k_{c}(x)}}z\right]\overline{s}(x, y)$$
(20)

and

$$\frac{\partial \overline{s}_c(x,y,z)}{\partial z}\Big|_{z=0} = \sqrt{\frac{S_{Sc}(x)p}{k_c(x)}} \coth\left[\sqrt{\frac{S_{Sc}(x)p}{k_c(x)}}\right] \overline{s}(x,y)$$
(21)

Substituting the above equation into equation (13) produces,

$$\frac{\partial^2 \overline{s}(x,y)}{\partial x^2} + \frac{\partial^2 \overline{s}(x,y)}{\partial y^2} - \frac{k_{sb}}{b_{sb}T(x)} [\mathcal{H}(x-x_{sl}) - \mathcal{H}(x-x_{sr})] \overline{s}(x,y)$$

$$- \frac{1}{T(x)} \sqrt{\frac{S_{Sc}(x)p}{k_c(x)}} \coth\left[\sqrt{\frac{S_{Sc}(x)p}{k_c(x)}}\right] \overline{s}(x,y) + \frac{Q}{pT(x)} \delta(x-x_p) \delta(y)$$

$$= p \frac{S(x)}{T(x)} \overline{s}(x,y) \qquad x_{lb} < x < x_{rb}, \qquad -\infty < y < \infty$$
(22)

## **IV.** Fourier-Laplace Space Equations

Applying a Fourier transform with respect to y to (22) and (14)-(16) produces:

$$\frac{d^{2}\widetilde{\overline{s}}(x)}{dx^{2}} - \omega^{2}\widetilde{\overline{s}}(x) - \frac{k_{sb}}{b_{sb}T(x)} [\mathcal{H}(x - x_{sl}) - \mathcal{H}(x - x_{sr})] \widetilde{\overline{s}}(x)$$

$$- \frac{1}{T(x)} \sqrt{\frac{S_{sc}(x)p}{k_{c}(x)}} \coth\left[\sqrt{\frac{S_{sc}(x)p}{k_{c}(x)}}\right] \widetilde{\overline{s}}(x) + \frac{Q}{\sqrt{2\pi}pT(x)} \delta(x - x_{p})$$

$$= p \frac{S(x)}{T(x)} \widetilde{\overline{s}}(x) \qquad x_{lb} < x < x_{rb}$$
(23)

$$\widetilde{\overline{s}}(x)\Big|_{x=x_{lb}} = 0 \quad or \quad \left.\frac{d\widetilde{\overline{s}}(x)}{dx}\right|_{x=x_{lb}} = 0$$
(24)

$$\widetilde{\overline{s}}(x)\Big|_{x=x_{rb}} = 0 \quad or \quad \left.\frac{d\widetilde{\overline{s}}(x)}{dx}\right|_{x=x_{rb}} = 0$$
(25)

where  $\tilde{\overline{s}}$  is the Fourier-Laplace transform of s, and  $\omega$  is the Fourier transform variable. Note the double overbar is used to indicate the dependence of s on p and  $\omega$ .

By defining,

$$\beta^{2} = \omega^{2} + \frac{k_{sb}}{b_{sb}T(x)} [\mathcal{H}(x - x_{sl}) - \mathcal{H}(x - x_{sr})] + \frac{1}{T(x)} \sqrt{\frac{S_{Sc}(x)p}{k_{c}(x)}} \coth\left[\sqrt{\frac{S_{Sc}(x)p}{k_{c}(x)}}\right] + p\frac{S(x)}{T(x)}$$
(26)

The above equation is simplified to,

$$\frac{d^2 \tilde{\overline{s}}(x)}{dx^2} - \beta^2 \tilde{\overline{s}}(x) + \frac{Q}{\sqrt{2\pi} p T(x)} \delta(x - x_p) = 0 \qquad x_{lb} < x < x_{rb}$$
(27)

The above equation is an ordinary differential equation (ODE) that is readily solved in the following section.

#### V. Transform-Space Solution

Dividing the aquifer into n zones of homogeneous properties in the x direction enables Eq. (27) to be written for each zone i as

$$\frac{d^2 \tilde{s}_i(x)}{dx^2} - \beta_i^2 \tilde{s}_i(x) + \frac{Q}{\sqrt{2\pi} p T(x)} \delta(x - x_p) = 0 \qquad x_i < x < x_{i+1}, \qquad i = 1, \dots n \quad (28)$$

Because  $\delta(x - x_p)$  vanishes when x is not equal to  $x_p$ , the general solution for the above equation is,

$$\tilde{s}_i(x) = c_{2i-1}\sinh(\beta_i x) + c_{2i}\cosh(\beta_i x)$$
  $x_i < x < x_{i+1}, \quad i = 1, ...n$  (29)

for bounded zones or

$$\tilde{\bar{s}}_i(x) = c_{2i-1}e^{\beta_i x} + c_{2i}e^{-\beta_i x} \qquad x_1 \to -\infty, \qquad x_{n+1} \to \infty$$
(30)

for unbounded zones. In all cases, the constant coefficients  $c_i$  are determined from the boundary conditions.

For external lateral boundary conditions, Eq. (24) and (25) are applied to  $x_1$  at the left boundary and to  $x_{n+1}$  at the right boundary, respectively. For inter-boundary conditions at  $x_i$  (i = 2, ...n), integrating Eq. (28) with respect to x across narrow regions containing  $x_i$  (i = 2, ...n) reveals that  $\tilde{s}_i(x)$  and its first derivative are continuous at all  $x_i$  (i = 2, ...n)except at  $x_p$   $(i = i_p)$  where the first derivative has a discontinuity because of the singular point at the pumping well. The boundary conditions can thus be written as,

$$\begin{aligned}
\left. \begin{array}{l} \text{Dirichlet} : \left. \widetilde{s}_{i}(x_{i}) \\ \text{Neumann} : \left. \frac{d\widetilde{s}_{i}(x)}{dx} \right|_{x=x_{i}} \right\} &= 0, \quad i = 1 \\ \left. \left( \widetilde{s}_{i}(x_{i+1}) - \widetilde{s}_{i+1}(x_{i+1}) \right) = 0, \quad i = 1, \dots, n-1 \\ \left. \left. \frac{d\left( \widetilde{s}_{i}(x) - \widetilde{s}_{i+1}(x) \right)}{dx} \right|_{x=x_{i+1}} \right|_{x=x_{i+1}} &= \left\{ \begin{array}{l} \frac{Q}{\sqrt{2\pi pT(x)}}, \quad i = i_{p} - 1 \\ 0, \quad all \ other \ i = 1, \dots, n-1 \end{array} \right. \\ \left. \begin{array}{l} \text{Dirichlet} : \left. \widetilde{s}_{i}(x_{i+1}) \\ \text{Neumann} : \left. \frac{d\widetilde{s}_{i}(x)}{dx} \right|_{x=x_{i+1}} \end{array} \right\} &= 0, \quad i = n \end{aligned} \right. \tag{31}
\end{aligned}$$

Substituting Eq. (29) into Eq. (31) produces,

$$\begin{aligned}
Dirichlet : \sinh(\beta_{i}x_{i})c_{2i-1} + \cosh(\beta_{i}x_{i})c_{2i} \\
Neumann : \cosh(\beta_{i}x_{i})c_{2i-1} + \sinh(\beta_{i}x_{i})c_{2i}
\end{aligned} = 0, \quad i = 1 \\
\sinh(\beta_{i}x_{i+1})c_{2i-1} + \cosh(\beta_{i}x_{i+1})c_{2i} \\
- & \sinh(\beta_{i+1}x_{i+1})c_{2i+1} - \cosh(\beta_{i+1}x_{i+1})c_{2i+2} = 0, \quad i = 1, ..., n-1 \\
& \beta_{i}\cosh(\beta_{i}x_{i+1})c_{2i-1} + \beta_{i}\sinh(\beta_{i}x_{i+1})c_{2i} - \beta_{i+1}\cosh(\beta_{i+1}x_{i+1})c_{2i+1} \\
- & \beta_{i+1}\sinh(\beta_{i+1}x_{i+1})c_{2i+2} = \begin{cases} \frac{Q}{\sqrt{2\pi}pT(x)}, & i = i_{p} - 1 \\ 0, & all \ other \ i = 1, ..., n-1 \end{cases} \\
& Dirichlet : \sinh(\beta_{i}x_{i+1})c_{2i-1} + \cosh(\beta_{i}x_{i+1})c_{2i} \\
& Neumann : \cosh(\beta_{i}x_{i+1})c_{2i-1} + \sinh(\beta_{i}x_{i+1})c_{2i} \end{cases} = 0, \quad i = n \end{aligned}$$
(32)

By defining

 $\sinh(\beta_i x_j) = a_{i,j}, \qquad \cosh(\beta_i x_j) = b_{i,j}, \qquad a_{i,i} = a_i, \qquad b_{i,i} = b_i$ (33)

Eq. (32) can be rewritten in a  $2n \times 2n$  matrix format, as shown in the following for which the left boundary is a Dirichlet condition and the right boundary is a Neumann condition,

The expression for  $\tilde{s}_i(x)$  can be obtained by solving the above linear equation for  $c_i$  and substituting the solution into Eq. (29).

For n = 4 zones with  $x = \{x_1, x_2, x_3, x_4, x_5\} = \{x_{lb}, x_{sl}, x_{sr}, x_p, x_{rb}\}$ , the above matrix equation can be simplified to,

$$= \begin{pmatrix} a_{1} & b_{1} & & & \\ a_{1,2} & b_{1,2} & -a_{2} & -b_{2} & & \\ \beta_{1}b_{1,2} & \beta_{1}a_{1,2} & -\beta_{2}b_{2} & -\beta_{2}a_{2} & & \\ & a_{2,3} & b_{2,3} & -a_{3} & -b_{3} & & \\ & & \beta_{2}b_{2,3} & \beta_{2}a_{2,3} & -\beta_{3}b_{3} & -\beta_{3}a_{3} & & \\ & & & a_{3,4} & b_{3,4} & -a_{4} & -b_{4} & \\ & & & & \beta_{3}b_{3,4} & \beta_{3}a_{3,4} & -\beta_{4}b_{4} & -\beta_{4}a_{4} & \\ & & & & b_{4,5} & a_{4,5} \end{pmatrix} \begin{pmatrix} c_{1} \\ c_{2} \\ c_{3} \\ c_{4} \\ c_{5} \\ c_{6} \\ c_{7} \\ c_{8} \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \frac{Q}{\sqrt{2\pi pT(x)}} \\ 0 \end{pmatrix}$$

Expressions for  $c_i$  and  $\tilde{s}_i$  are very lengthy and not provided here for the sake of brevity. A Mathematica notebook is available for interested readers. However, the expressions used for all examples in *Butler et al.* [in review] are presented in the Section VII.

## VI. Transform-Space Solution for Unbounded Domain

For an unbounded domain in the x direction,  $x_{lb} = -\infty$  and  $x_{rb} = \infty$ , an approach similar to that in Section V is adopted to derive the boundary conditions in which Eq. (30) is used for the unbounded (far left and far right) zones.

$$c_{2i} = 0, \quad i = 1$$

$$e^{\beta_{i}x_{i+1}}c_{2i-1} - \sinh(\beta_{i+1}x_{i+1})c_{2i+1} - \cosh(\beta_{i+1}x_{i+1})c_{2i+2} = 0, \quad i = 1$$

$$\beta_{i}e^{\beta_{i}x_{i+1}}c_{2i-1} - \beta_{i+1}\cosh(\beta_{i+1}x_{i+1})c_{2i+1}$$

$$- \beta_{i+1}\sinh(\beta_{i+1}x_{i+1})c_{2i+2} = \begin{cases} \frac{Q}{\sqrt{2\pi}pT(x)}, \quad i = i_{p} - 1 = 1 \\ 0, \quad i = 1 \neq i_{p} - 1 \end{cases}$$

$$\sinh(\beta_{i}x_{i+1})c_{2i-1} + \cosh(\beta_{i}x_{i+1})c_{2i} = 0, \quad i = 2, ..., n - 2$$

$$\beta_{i}\cosh(\beta_{i}x_{i+1})c_{2i-1} + \beta_{i}\sinh(\beta_{i}x_{i+1})c_{2i} - \beta_{i+1}\cosh(\beta_{i+1}x_{i+1})c_{2i+1}$$

$$- \beta_{i+1}\sinh(\beta_{i+1}x_{i+1})c_{2i+2} = \begin{cases} \frac{Q}{\sqrt{2\pi}pT(x)}, \quad i = i_{p} - 1 \\ 0, \quad all \ other \ i = 2, ..., n - 2 \end{cases}$$

$$\sinh(\beta_{i}x_{i+1})c_{2i-1} + \cosh(\beta_{i}x_{i+1})c_{2i} - e^{-\beta_{i+1}x_{i+1}}c_{2i+2} = 0, \quad i = n - 1$$

$$\beta_{i}\cosh(\beta_{i}x_{i+1})c_{2i-1} + \beta_{i}\sinh(\beta_{i}x_{i+1})c_{2i}$$

$$- \beta_{i+1}e^{-\beta_{i+1}x_{i+1}}c_{2i+2} = \begin{cases} \frac{Q}{\sqrt{2\pi}pT(x)}, \quad i = i_{p} - 1 \\ 0, \quad all \ other \ i = n - 1 \neq i_{p} - 1 \\ 0, \quad all \ other \ i = n - 1 \neq i_{p} - 1 \end{cases}$$

$$(34)$$

By applying Eq. (33) and redefining

$$e^{\beta_1 x_2} = a_{1,2} = b_{1,2} \qquad e^{-\beta_n x_n} = a_n = b_n \tag{35}$$

Eq. (34) can be rewritten in a  $2n \times 2n$  matrix format, as shown in the following for which left boundary is a Dirichlet condition and the right boundary is a Neumann condition,

$$= \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \frac{\sqrt{2\pi}pT(x)}{\sqrt{2\pi}pT(x)}, & i = i_p - 1 \\ 0, & all \ other \ i = 1, ..., n - 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

The expression for  $\tilde{s}_i(x)$  can be obtained by solving the above linear equation for  $c_i$  and substituting the solution into Eq. (29) or (30).

For n = 4 zones with  $x = \{x_1, x_2, x_3, x_4, x_5\} = \{x_{rl} = -\infty, x_{sl}, x_{sr}, x_p, x_{rb} = \infty\}$ , the above matrix equation is written as,

$$\begin{pmatrix} 0 & 1 & & & & \\ a_{1,2} & 0 & -a_2 & -b_2 & & & \\ \beta_1 b_{1,2} & 0 & -\beta_2 b_2 & -\beta_2 a_2 & & & \\ & & a_{2,3} & b_{2,3} & -a_3 & -b_3 & & \\ & & & \beta_2 b_{2,3} & \beta_2 a_{2,3} & -\beta_3 b_3 & -\beta_3 a_3 & & \\ & & & & a_{3,4} & b_{3,4} & 0 & -b_4 \\ & & & & & & a_{3,4} & \beta_3 a_{3,4} & 0 & -\beta_4 a_4 \\ & & & & & & & 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \\ c_7 \\ c_8 \end{pmatrix} = \begin{pmatrix} 0 & & \\ 0 & &$$

A Mathematica notebook is available for interested readers with expressions for  $c_i$  and  $\tilde{s}_i$ . Expressions for the simple unbounded and homogeneous system used for all examples in *Butler et al.* [in review] are presented in the next section.

# VII. Transform-Space Solution for Unbounded Homogeneous Aquifer

For a homogeneous domain and the zone underneath the stream  $(x_{sl} < x < x_{sr})$ , Eq. (26) can be simplified to

$$\beta_s^2 = \omega^2 + \frac{k_{sb}}{b_{sb}T} + \frac{1}{T}\sqrt{\frac{S_{Sc}p}{k_c}} \coth\left[\sqrt{\frac{S_{Sc}p}{k_c}}\right] + p\frac{S}{T}$$
(36)

Outside that zone, the equation can be further simplified to

$$\beta^2 = \omega^2 + \frac{1}{T} \sqrt{\frac{S_{Sc}p}{k_c}} \coth\left[\sqrt{\frac{S_{Sc}p}{k_c}}\right] + p\frac{S}{T}$$
(37)

Given the homogeneous domain, the problem can be reduced to solving a group of linear equations for four zones, the boundaries of which are defined by the pumping well and by the two sides of the stream:

$$\widetilde{\overline{s}}(x) = \begin{cases} \sqrt{\frac{2}{\pi}} Q \beta_s e^{-(x_p - x_{sr} + x_{sl} - x)\beta - (x_{sr} - x_{sl})\beta_s} \frac{1}{D}, & -\infty < x < x_{sl} \\ \frac{1}{\sqrt{2\pi}} Q e^{-(x_p - x_{sr})\beta - (x_{sr} + x - 2x_{sl})\beta_s} \\ (e^{2(x - x_{sl})\beta_s} (\beta + \beta_s) - (\beta - \beta_s)) \frac{1}{D}, & x_{sl} < x < x_{sr} \\ -\frac{1}{\sqrt{2\pi}} Q \frac{1}{2\beta} e^{-(x_p + x)\beta - 2x_{sr}\beta_s} \\ ((e^{2x\beta} + e^{2x_{sr}\beta})(e^{2x_{sr}\beta_s} - e^{2x_{sl}\beta_s})\beta^2 \\ 2e^{2x\beta} (e^{2x_{sr}\beta_s} + e^{2x_{sl}\beta_s})\beta\beta_s \\ (e^{2x\beta} - e^{2x_{sr}\beta})(e^{2x_{sr}\beta_s} - e^{2x_{sl}\beta_s})\beta^2 \\ \frac{1}{\sqrt{2\pi}} Q \frac{1}{2\beta} e^{-(x_p + x)\beta - 2x_{sr}\beta_s} \\ ((e^{2x_p\beta} + e^{2x_{sr}\beta})(e^{2x_{sr}\beta_s} - e^{2x_{sl}\beta_s})\beta^2 \\ 2e^{2x_p\beta} (e^{2x_{sr}\beta_s} + e^{2x_{sl}\beta_s})\beta\beta_s \\ (e^{2x_p\beta} - e^{2x_{sr}\beta})(e^{2x_{sr}\beta_s} - e^{2x_{sl}\beta_s})\beta^2_s) \frac{1}{D}, & x_p < x < \infty \end{cases}$$
(38)

in which

$$D = pT(e^{2(x_{sr} - x_{sl})\beta_s}(\beta - \beta_s)^2 - (\beta + \beta_s)^2).$$

For the case of an impermeable formation underlying the shallow aquifer of Fig. 1, the leakage (coth) term in Eq. (36) and (37) is negligible, resulting in:

$$\beta_s^2 = \omega^2 + \frac{k_{sb}}{b_{sb}T} + p\frac{S}{T}$$
(39)

for the zone underneath the stream  $\left( x_{sl} < x < x_{sr} \right)$  and

$$\beta^2 = \omega^2 + p \frac{S}{T} \tag{40}$$

for all other zones. The solution is thus the same as Eq. (38) except for the definitions of  $\beta$  and  $\beta_s.$ 

# VIII. Transform-Space Solution for Stream Depletion

The rate of stream depletion  $\Delta q$  is defined as the total volumetric discharge across the incompressible streambed at any given time (see Fig. 1 and caption). For the simplified scenario of Fig. 1 and the previous section,  $\Delta q$  can be expressed as:

$$\Delta q(t) = \frac{k_{sb}}{b_{sb}} \int_{-\infty}^{\infty} \int_{x_{sl}}^{x_{sr}} s_s dx dy \tag{41}$$

in which  $s_s$  is the drawdown beneath the stream.

Application of the Laplace transform to Eq. (41) and switching the x and y integrals yields:

$$\Delta \bar{q}(p) = \frac{k_{sb}}{b_{sb}} \int_{x_{sl}}^{x_{sr}} \int_{-\infty}^{\infty} \bar{s_s} dy dx = \frac{k_{sb}}{b_{sb}} \int_{x_{sl}}^{x_{sr}} \tilde{s_s} dx \tag{42}$$

in which  $\Delta \bar{q}(p)$  is the Laplace transform of  $\Delta q$  and  $\tilde{s}_s$  is the Fourier-Laplace transform of  $s_s$  for  $\omega = 0$ :

Substitution of Eq. (38) into Eq. (42) and performing the integration results in:

$$\Delta \bar{q}(p) = -\frac{1}{\sqrt{2\pi}} Q e^{-(x_p - x_{sr})\beta} (e^{x_{sr}\beta_s} - e^{x_{sl}\beta_s}) \frac{1}{D_s}$$

$$\tag{43}$$

in which

$$D_s = pT((e^{x_{sr}\beta_s} + e^{x_{sl}\beta_s})\beta\beta_s + (e^{x_{sr}\beta_s} - e^{x_{sl}\beta_s})\beta_s^2).$$

## IX. Numerical Inversion of Laplace-Fourier Space Solutions

The solutions in Laplace-Fourier space given in the previous sections are most readily evaluated using a numerical inversion scheme. A Mathematica Add-On package prepared by *Mallet* [2000] is used for the joint Laplace-Fourier numerical inversion. This package provides five inversion methods to invert Laplace transforms and joint Fourier/Hankel-Laplace transforms. The inversion techniques are those of *Durbin* [1974], *Stehfest* [1970], *Weeks* [1966], *Piessens* [1971], and *Crump* [1976]. The *Stehfest* [1970] algorithm, the most commonly used inversion algorithm for well-hydraulics applications, is selected for the inversion of head responses and stream depletion from Laplace space. The Fourier inversion uses the symbolic inverse Fourier transform provided in Mathematica.

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